New HW features and improvements 2022

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Logging modules 2022 - Overview

Overview can be downloaded as pdf here!

The data presented here in the overview always refers to the most comprehensive firmware of the respective module. For many modules there are reduced firmware versions (see *Option*), for which more information can be found in the respective data sheets.

Name	Logging		CAN-Bus						Analog Inputs			Calc channels	Output channels	IMU	Serial GPS/GNSS	RS232	Frequency Inputs	Max. Ethernet	XCP/CCP	Size [mm]	Notes	Link	
	Internal	Sticklogging	Lines	FD	Max. ONLINE CAN channels	Streamlogging	Max. CAN speed	Max. sampling rate	CAN-Routing	Max. Inputs	Max. Samplingrate	Resolution				Input			Ports				
						Option		Option	Option		Option				Option					Option			
Logger 9	32 GB	✓	4	×	512	×	2 Mbit/s	1000 Hz	~	32	10000 Hz	16 Bit (HQ)	16	2	×	*	1	4 (up to 100 Khz)	2	CCP/XCP ASAM 1.4 CAN/CAN- FD/Ethernet	76 x 90 x 26		<u>Datasheet</u>
Sticklogger V1	32 MB	✓	1	×	128*	(Stream-FW required)	1 Mbit/s	1000 Hz	×		×		8	1	×	~	×	×	×	CCP ASAM 1.0 CAN	70 x 40 x 13	Available for OEM costumers only	<u>Datasheet</u>
Sticklogger V2	32 MB	✓	2	×	128*	(Stream-FW required)	1 Mbit/s	1000 Hz	~	2	16000 Hz	16 Bit	24	1	6 axis IMU (optional)	(with RTK)	×	×	×	CCP/XCP ASAM 1.4 CAN	70 x 40 x 13		<u>Datasheet</u>
Sticklogger V3	32 MB	✓	2	×	128*	(Stream-FW required)	2 Mbit/s	2000 Hz	~	4 (1 can be used as Hybrid input)	16000 Hz	16 Bit	24	1	6 axis IMU (optional)	×	×	1 (up to 50 Khz)	×	CCP/XCP ASAM 1.4 CAN	70 x 40 x 13		<u>Datasheet</u>
Sticklogger V4	32 MB	✓	2	×	128*	(Stream-FW required)	2 Mbit/s	2000 Hz	~	4 (1 can be used as Hybrid input)	16000 Hz	16 Bit	24	1	6 axis IMU (optional)	(with RTK)	×	1 (up to 50 Khz)	×	CCP/XCP ASAM 1.4 CAN	70 x 50 x 15	Available with built-in Wi-Fi module **	<u>Datasheet</u>
Sticklogger V5	32 MB	✓	3	1	128*	(Stream-FW required)	5 Mbit/s	2000 Hz	~	8 (2 can be used as Hybrid input)	16000 Hz	16 Bit	32 / 64	1	×	(with RTK)	×	2 (up to 50 Khz)	1	CCP/XCP ASAM 1.4 CAN/CAN- FD/Ethernet	100 x 70 x 16	Available with built-in Wi-Fi module **	<u>Datasheet</u>
Cargo Security	2 GB	×	2	×	128	×	2 Mbit/s	1000 Hz	~	4	1000 Hz	16 Bit	32	1	6 axis IMU	~	×	×	×	×	100 x 73.1 x 30	Battery powered Screw mounting IP65	<u>Datasheet</u>
LED Bar	32 MB	 ✓ 	2	×	32	(Stream-FW required)	2 Mbit/s	1000 Hz	~		×		24	×	×	×	×	×	×	CCP/XCP ASAM 1.4 CAN	62 x 32.5 x 15	10 progrm. Multi color LED	Datasheet
ColorDash	×	✓	3	1	128*	(Stream-FW required)	5 Mbit/s	1000 Hz	~	4	1000 Hz	16 Bit	32 / 64	1	×	(with RTK)	×	1 (up to 50 Khz)	×	CCP/XCP ASAM 1.4 CAN/CAN- FD/Ethernet	96 x 60 x 20	Available with built-in Wi-Fi module **	<u>Datasheet</u>

* With Streamlogger firmware (available from 2021 and for Stickloggers and Dashboards) a measurement with an "unlimited" number of OFFLINE CAN-channels can be created! At Streamlogging all on CAN bus received CAN identifiers are recorded with unique time stamp and subsequently linked to a CAN-DB/DBC-file in postprocessing to create 2D Analyzer channels.

* With built-in Wi-FI module for wireless Winlt communcation for setting changes and as RealDash interface for live displaying CAN-values on indivually designable dashboards for smartphone/tablet/computer!

For all Stickloggers from 2022 on a "OneFileRecording"-firmware is available!

This FW does not write into the FAT of the USB Stick anymore.

Due to this change, the chance of loosing data during power fail/drop is eliminated.

All StickLoggers can be delivered with either old style - /OF- or OFStream firmware.

Improved Sticklogging - One File Recording

Background

The new 2D One File Recording improves data security/integrity when recording to the USB stick when it is unplugged, or the system is switched off while data is being written to it. This is achieved by completely avoiding writing to the file system table of the USB stick. Logger settings and measurement data are now written to the same container file.

All known features of Stickloggers remaining the same, just the USB-Stick recording is improved significantly!

OneFileRecording can also be used with Streamlogging!

Requirements to use One File Recording

At least Sticklogger FW 95 (better 105 ++)

At least Race2022 Software

Streamlogging

Sticklogger	Streamlogger
Only records its CAN channels which are <u>defined by the previously done setting (.LDD)</u>	Records all on CAN Bus received CAN identifiers with unique time stamp.
Stickloggers can only record max. 128 ONLINE CAN channels	With Streamloggers max. 128 ONLINE CAN channels can be recorded <u>plus</u> a measurement with an <u>unlimited</u> number of OFFLINE CAN 2D Analyzer channels can be created at decompressing!
Recorded CAN channels are immediately available after download	Recorded (raw) CAN identifier data must be linked to a CAN-DBC file at decompressing (only in CAN-DBC file used channels will be created as 2D-channels for Analyzer)
	Recorded (raw) CAN identifier data can be used for creating different 2D measurements multiple times
	Streamlogger can also record <u>certain</u> defined CAN channels (.LDD) and all on CAN Bus received CAN channels, which must be decompressed with DBC, at same time.



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<u>2D</u>

Streamlogging

Further information

An important difference to Sticklogger is that Streamlogger, in addition to all known Sticklogger functions, can also record all messages sent on the CAN bus, allowing measurements to be made with an unlimited number of OFFLINE CAN channels!

So, the difference in Stick-and Streamlogging is only in behaviour of CAN-Bus channel logging because of another firmware!

With Streamlogger still 128 ONLINE CAN bus channels can be used for recording and other purposes like sending channels via CAN or using in CALC channels!

Stream- and Stickloggers can be still used for recording multiple CAN bus.

Because DashTFT is also able to record data, Streamlogging firmware is also available for DashTFT!

Total datarates Stick-&Streamlogger for writing on USB-stick:

- V2/3/4 → 500 kByte/s (for recording channels from CAN-1 + CAN-2 + internal channels, data rate from single 1 Mbit CAN channel is max. max. 100 kByte/s)
- V5 → 3000 kbyte/s (for recording channels from CAN-1 + CAN-2 + internal channels, single CAN Bus with max. 100 kByte/s)

Requirements to use Streamlogging

At least Streamlogger FW 105

At least Race2022 Software

Streamplay

With Streamlogging it is possible to replay the original measurement with all its CAN messages (also GPS data if received via CAN) in real time and as often as desired!

This makes it possible to perform tests with real race track data in the office/garage, e.g. to test a display setting or GPS laptiming setting.

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- New converter for A2L 1.4 definition

Ldd file creation from A2L definition CAN-DB file creation

XCP communication with "unlimited" number of channels via...

...CAN-bus ...CAN-FD ...Ethernet

Further information

Import and export of ASAM MDF measurements and Vector ASC or BLF CAN Streams Analyze and Export Automotive Standard CAN Recording formats with 2D Software and Loggers.

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Dashboards

ColorDash (Link to website)

Fully programmable dashboard 3" with sunlight readable 1000 nits, true colour TFT display

USB Sticklogging capabilities

Light and robust metal housing

Font and background color are individually adjustable in relation to the channel value

17 fully programmable high brightness RGB LED with 5ms reaction time with shift light bar function

Predictive laptiming



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Dashboards

GAP event (YouTube video)

The GAP time function is used to constantly indicate the current time difference to the same position in a reference lap.

A <u>negative</u> GAP time means that at the current position the driver is <u>ahead</u> the current position at reference lap, so the laptime is faster.

A positive GAP time means that at the current position the driver is behind the current position at reference lap, so the laptime is slower.



GPS/GNSS modules

New GNSS modules (click here to download manual)

New modules and firmware have greatly improved the stability and reliability of the GPS/GNSS signals, as the satellites of all four major (GPS, Galileo, Glonass, Beidou) Global Navigation Satellite Systems (GNSS) are now used, not just GPS!

Access to many more GNSS satellites greatly increases the positional accuracy of the GNSS modules, especially in difficult receiving environments such as cities or forests.

Please click <u>here</u> for further information about the best GNSS antenna for your application!

Following overview can be downloaded as pdf here!

Available since	Serial	CAN	Name	Rate	GPS/ GNSS	CEP	IMU	RTK	Notes	Link		
2000	✓	×	10 Hz Mouse	10 Hz	GPS	3.00 m 🗴		×	KIT antenna	<u>Website</u>		
2000	~		12.5 Hz Mouse	12.5 Hz	GPS	2.50 m	×					
(2021)		×	10 Hz Mouse	10 Hz	GNSS	1.50 m		×	With Logger-Firmware > 100 the 12.5 Hz Mouse can also be set via Logger setting** to 10 Hz to receive signals from all GNSS instead of just GPS, which improves positional accuracy.	<u>Website</u>		
2021	✓	×	25 Hz Mouse	25 Hz	GNSS	< 1.00 m	×	×	Logger-Firmware > 100 required to use 25 Hz Mouse	<u>Website</u>		
	×			12.5 Hz	GPS 2.50 m							
2015		1	GPS2CAN*	10 Hz	GNSS	x 1.50 m	×	- *	Via firmware update of GPS2CAN modules from 2019+ can receive signals from all GNSS instead of just GPS, which improves positional accuracy. Update reduces the rate from 12.5 to 10 Hz.	Website		
(2021)			GPS2CAN_3A3G*	12.5 Hz	GPS	2.50 m				website		
				10 Hz	GNSS	✓ 1.50 m	•		Via firmware update of GPS2CAN modules from 2019+ can receive signals from all GNSS instead of just GPS, which improves positional accuracy. Update reduces the rate from 12.5 to 10 Hz.			
2021			GNSS2CAN*	05.11-	0100	4 00	×			Mahaita		
	*	•	GNSS2CAN_3A3G*	25 HZ	GNSS	< 1.00 m	✓	- x		website		
2022	✓	×	10 Hz RTK	10 Hz	GNSS	0.01 m	×	~	Logger-Firmware > 100 required to use RTK functionality			
* The updat	te to GP	S/GN	ISS2CAN modules wit	th/witho	ut IMU i	s done via	firmware	updat	e and can therefore be carried out at any time!			
** Set all G	** Set all GPS channels of Logger to sampling rate 10 Hz to receive signals from all GNSS instead of GPS only!											

GPS/GNSS modules

<u>RTK (Real Time Kinematic)</u>

By using the RTK functionality, the accuracy of position data derived from GNSS is improved significantly!

It uses measurements of the phase of the carrier wave of the signal in addition to the information content of the signal and relies on a base station to provide real-time corrections that offer accuracy of up to one centimetre (±1cm)!



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WIFI2CAN module

2D Communication

Similar to USB2CAN the WIFI2CAN module allows to communicate to all 2D-CAN-modules of a 2D system via Wi-Fi. In comparison to USB2CAN, the WIFI2CAN does not need any physical connection to the system to communicate with.



2D DATARECORDING

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WIFI2CAN module

<u>RealDash-Gateway</u>

Visualizing CAN data received via WIFI from measurement system on individually designed dashboards on any device (PC, tablet, smartphone)





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2D DATARECORDING

BLE2CAN module

Bluetooth Low Energy - Heart Rate receiver

Via the BLE2CAN module, a rider's heart rate can be received and sent to a logger for recording via CAN, allowing conclusions to be drawn about physical exertion on track. The BLE2CAN module can be ordered as a set with a heart rate sensor with chest strap already connected.



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Sound link

<u>Audio file import</u>

(multichannel) .wav files can be imported into the measurement as analogue channels and than processed with CalcTool

Audio data recording

Audio signals from microphones (rider comments, exhaust noise, etc.) can be recorded as analgoue channel

Audio data filtering

Analog sound data can be filtered and analysed with CalcTool and Analyzer

Audio file conversion/export

Analog sound data can be converted into audio data by exporting as .wav file

Audio file replay

Audio files (.wav) can be imported and synchronized to measruement data and playback with VideoPlugin